

where the matrix $Q_t^{[k]}$ is defined as follows:

$$(13.35) \quad Q_t^{[k]} = Q_t + H_m \Sigma_{c_t, t-1}^{[k]} H_m^T$$

To see, we note that under our linear approximation the convolution theorem provides us with a closed form for the integral term in (13.27):

$$(13.36) \quad \mathcal{N}(z_t; \hat{z}_t^{[k]} + H_x x_t - H_x \hat{x}_t^{[k]}, Q_t^{[k]})$$

The sampling distribution (13.27) is now given by the product of this normal distribution and the rightmost term in (13.27), the normal $\mathcal{N}(x_t; \hat{x}_t^{[k]}, R_t)$. Written in Gaussian form, we have

$$(13.37) \quad p(x_t | x_{1:t-1}^{[k]}, u_{1:t}, z_{1:t}, c_{1:t}) = \eta \exp \left\{ -P_t^{[k]} \right\}$$

with

$$(13.38) \quad P_t^{[k]} = \frac{1}{2} \left[(z_t - \hat{z}_t^{[k]} - H_x x_t + H_x \hat{x}_t^{[k]})^T Q_t^{[k]-1} (z_t - \hat{z}_t^{[k]} - H_x x_t + H_x \hat{x}_t^{[k]}) + (x_t - \hat{x}_t^{[k]})^T R_t^{-1} (x_t - \hat{x}_t^{[k]}) \right]$$

This expression is obviously quadratic in our target variable x_t , hence $p(x_t | x_{1:t-1}^{[k]}, u_{1:t}, z_{1:t}, c_{1:t})$ is Gaussian. The mean and covariance of this Gaussian are equivalent to the minimum of $P_t^{[k]}$ and its curvature. Those are identified by calculating the first and second derivatives of $P_t^{[k]}$ with respect to x_t :

$$(13.39) \quad \begin{aligned} \frac{\partial P_t^{[k]}}{\partial x_t} &= -H_x^T Q_t^{[k]-1} (z_t - \hat{z}_t^{[k]} - H_x x_t + H_x \hat{x}_t^{[k]}) + R_t^{-1} (x_t - \hat{x}_t^{[k]}) \\ &= (H_x^T Q_t^{[k]-1} H_x + R_t^{-1}) x_t - H_x^T Q_t^{[k]-1} (z_t - \hat{z}_t^{[k]} + H_x \hat{x}_t^{[k]}) - R_t^{-1} \hat{x}_t^{[k]} \end{aligned}$$

$$(13.40) \quad \frac{\partial^2 P_t^{[k]}}{\partial x_t^2} = H_x^T Q_t^{[k]-1} H_x + R_t^{-1}$$

The covariance $\Sigma_{x_t}^{[k]}$ of the sampling distribution is now obtained by the inverse of the second derivative

$$(13.41) \quad \Sigma_{x_t}^{[k]} = \left[H_x^T Q_t^{[k]-1} H_x + R_t^{-1} \right]^{-1}$$

The mean $\mu_{x_t}^{[k]}$ of the sample distribution is obtained by setting the first derivative (13.39) to zero. This gives us:

$$(13.42) \quad \begin{aligned} \mu_{x_t}^{[k]} &= \Sigma_{x_t}^{[k]} \left[H_x^T Q_t^{[k]-1} (z_t - \hat{z}_t^{[k]} + H_x \hat{x}_t^{[k]}) + R_t^{-1} \hat{x}_t^{[k]} \right] \\ &= \Sigma_{x_t}^{[k]} H_x^T Q_t^{[k]-1} (z_t - \hat{z}_t^{[k]}) + \Sigma_{x_t}^{[k]} \left[H_x^T Q_t^{[k]-1} H_x + R_t^{-1} \right] \hat{x}_t^{[k]} \\ &= \Sigma_{x_t}^{[k]} H_x^T Q_t^{[k]-1} (z_t - \hat{z}_t^{[k]}) + \hat{x}_t^{[k]} \end{aligned}$$